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PLD Autumn 2016 Signals and Linear Systems Lecture 1 Slide 3 Aims and Objectives By the end of the course, you will have understood: - Basic signal analysis (mostly continuous-time) - Basic system analysis (also mostly continuous systems) - Time-domain system analysis (including convolution) - Laplace and Fourier Transform - System Analysis in Laplace and Fourier Domains

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This is in the form of a first-order difference equation with input signal $\delta[n]$ and output signal $g[n]$. That is, $g[n]$ is the impulse response of the LTI system. A characteristic root is the same as a pole in the transfer function in the z-domain for an LTI system. Midterm #1, Fall 2010, Problem 1.5. Discrete-time systems part only.

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