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Looking at the figure, we see that: $\dot{u} = 9.5 \text{ ? } 10.0 \text{ lps} = 70.5 \text{ lps slope} = 0.3 \text{ ? } 1 \text{ m } 10 \text{ ? } 3 \text{ min} = 70.1 \text{ m min}$ We can then calculate the gain using the formula: $kp = \text{slope} \text{ ? } u \text{ } kp = 70.1 \text{ m min } 70.5 \text{ lps} = 0.2 \text{ m min} \cdot \text{lps}$ The integrator plus dead time model is thus: $gp(s) = 0.2e^{-2s} s^{-4-2}$ Process Control Modeling Design And Simulation 1st Edition Bequette Solutions Manual Full ...

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