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Introduction to Control Theory, 2nd Edition. Oxford University Press. Julier⁹⁶ Julier, Simon and Jeffrey Uhlman. [A General Method of Approximating Nonlinear Transformations of Probability Distributions,] Robotics Re- search Group, Department of Engineering Science, University of Oxford [cited 14 November 1995].

Introduction to Control System

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Control Systems - Introduction - Tutorialspoint

Modern control methods were introduced in the early 1950's, as a way to bypass some of the shortcomings of the classical methods. Rudolf Kalman is famous for his work in modern control theory, and an adaptive controller called the Kalman Filter was named in his honor. Modern control methods became increasingly popular after 1957 with the invention of the computer, and the start of the space program.

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In both cases, this is the second control-like course taken by the students. The main goal of these notes is to provide a self-contained and rigorous background on systems theory and an introduction to state space analysis and design methods for linear systems. In preparing these notes I was deeply influenced by the approach pursued in the book

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