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a) Design a state feedback controller for the following system so that the closed-loop step response has an overshoot of less than 5% and a 1% settling time under 4.6 sec. b) Use the step command in MATLAB to verify that your design meets the specifications. If it does not, modify your feedback gains accordingly.

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For (a) and (b), state whether you think the system will eventually de-cay so that it has no motion at all, given that there are non-zero initial conditions for both masses, and give a reason for your answer. Fig. 2.41 Mechanical systems Solution: The key is to draw the Free Body Diagram (FBD) in order to keep the signs right.

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