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A comprehensive treatment of the analysis and design of discrete-time control systems which provides a gradual development of the theory by emphasizing basic concepts and avoiding highly mathematical arguments. The book features comprehensive treatment of pole placement, state observer design, and quadratic optimal control.

*Discrete-Time Control Systems by Katsuhiko Ogata (1994 ...*

Such a discrete-time control system consists of four major parts: 1 The Plant which is a continuous-time dynamic system. 2 The Analog-to-Digital Converter (ADC). 3 The Controller ( $\mu P$ ), a microprocessor with a "real-time" OS. 4 The Digital-to-Analog Converter (DAC) .

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Figure 1: A discrete time control input with zero order hold applied to a continuous time system.  $G_k(j) = \frac{1}{s} G(s)$  : (11) For stability, the eigenvalues of  $G$  must have magnitude  $< 1$ . So if the continuous time plant is stable ( $\text{eig}(A) < 0$ ) the discrete time plant will have eigenvalues with magnitude less than 1.

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*Plane Analysis of Discrete-Time Systems. 4. Design of Discrete-Time Control Systems by Conventional Methods. 5. State Space Analysis. 6. Pole Placement and Observer ...*

*Discrete-Time Control Systems 1995.*

*Discrete time control systems. The standard number system used for processing digital signals is the binary number system. In this system the code group consists of  $n$  pulses each indicating either "on" (1) or "off" (0). In the case of quantizing,  $n$  "on-off" pulses can represent  $2^n$  amplitude levels or output states.*

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*DiscreteTimeControlSystems*

*Ogata wrote this textbook for senior undergraduate or first-year graduate students in engineering who have taken an introductory course in control systems as well as one in differential equations; familiarity with MATLAB is recommended.*

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