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In sociology, control theory is the view that people refrain from deviant behavior because diverse factors control their impulses to break social norms. Developed by thinkers such as Travis Hirschi and Walter Reckless in the late 1960s and early 1970s, control theory explains why people often do not act on deviant impulses.

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-motor program-based theory and dynamical systems are predominate- motor control theory cannot focus exclusively on movement info specified by CNS (task and overrun. condition must be taken into account too)-speculation exists that hybrid of the two theories as a compromise theory could emerge to explain control of coordinated movement

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personal choice and that people
can freely choose to participate in
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- a side by side integration theory
that also has some up and down
integration - combines control,
learning, deterrence, and rational
choice theories. - This theory is
about how much control the
individual is subject to and how
much control the individual can
exert on him/herself - Control
deficits Predatory Defiant
Submissive behaviors ...**

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**Framed in this way, the dynamics of
the falling cat problem is a**

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prototypical example of a nonholonomic system (Batterman 2003), the study of which is among the central preoccupations of control theory. A solution of the falling cat problem is a curve in the configuration space that is horizontal with respect to the connection (that is, it is ...

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ECON 402: Optimal Control Theory
6 3 The Intuition Behind Optimal
Control Theory Since the proof,
unlike the Calculus of Variations, is
rather di cult, we will deal with the
intuition behind Optimal Control
Theory instead. We will make the
following assump-tions, 1. uis
unconstrained, so that the solution
will always be in the interior. In

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other

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engineering and mathematics,
control theory deals with the beha
viour of dynamical systems. The
desired output of a system is called
the reference. When one or more
output variables of a system need
to follo w a certain ref-**

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