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Troubleshooting
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EXAMPLE

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Review and Preview of
Control Computer-
Aided-Design of
Control Systems: There
will be several design
problems where you
will be expected to use
the theoretical concepts
from the course and the
CAD package
MATLAB to design
controllers for various

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physical systems (e.g.,
motors, aircraft, robots,
etc.).

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Construction of Root
Locus - The root locus
is a graphical
representation in s-
domain and it is
symmetrical about the
real axis. Because the

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open loop poles and zeros exist in the s -domain ... In this way, you can draw the root locus diagram of any control system and observe the movement of poles of the closed loop transfer function.

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Control systems

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E Introduction

ANSWERS TO

REVIEW QUESTIONS

1. Guided missiles,
automatic gain control
in radio receivers,
satellite tracking
antenna 2. Yes - power
gain, remote control,
parameter conversion;
No - Expense,
complexity 3.

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2.04A Systems and
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Problem 2

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discuss about top five
problems on budget and
budgetary control with
their relevant solutions.

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Problem 1 with Solution
Budget and Budgetary

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EXAMPLE

PROBLEMS AND
SOLUTIONS A-3-1.

Simplify the block
diagram shown in
Figure 3-42. Solution.

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First, move the branch point of the path involving H_1 outside the loop involving H_2 , as shown in Figure 3-43(a). Then eliminating two loops results in Figure 3-43(b). Combining two

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Page . The concepts

discussed in the

previous chapter are

helpful for reducing

(simplifying) the block

diagrams. Block

Diagram Reduction

Rules. Follow these

rules for simplifying

(reducing) the block

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diagram, which is
having many blocks,
summing points and
take-off ...

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solutions. By Nick Peers
(PCAnswers Issue 215)

... open the System
Control Panel and either

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click "Advanced system settings" or switch to the Advanced tab.

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problems in Control
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January, 2017 - updates:

12/2017 - 03/01/2020 -

04/01/2020 01) Let a

plant be represented by
the transfer function

between the input u and
the output y given by

$P(s) = \frac{1}{s^2}$ Determine,

in a feedback control
scheme, a controller

such that at steady-

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